

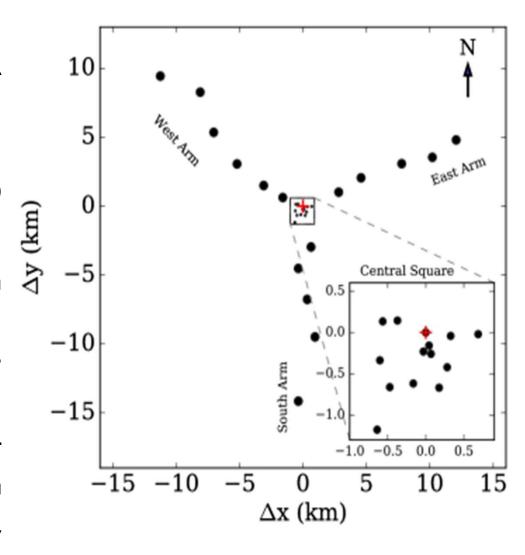
Giant Metrewave Radio Telescope (GMRT): A System Overview

Kaushal D. Buch
Giant Metrewave Radio Telescope (GMRT), NCRA,
Tata Institute of Fundamental Research
kdbuch@gmrt.ncra.tifr.res.in

June 10 2021 (Online session)

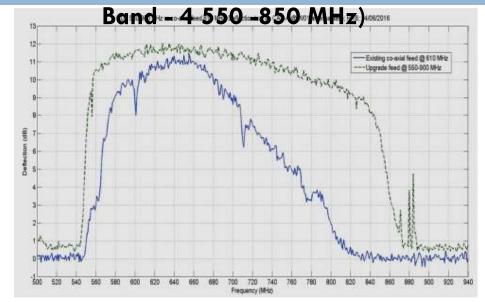
Giant Metrewave Radio Telescope

- Sensitive telescope operating between 150 to 1450 MHz. A national project of the Govt. of India
- Located 80 km north of Pune, 160 km east of Mumbai
- □ Array telescope: 30 antennas, each ₹
 of 45 m diameter 14 antennas in 1
 sq. km. region, other spread in a Y shaped array
- Central square (C00 C14, except C07), E-arm (E02-E06), W-arm (W01-W06), S-arm (S01-S06, except S05)



The Upgraded GMRT

- Near seamless observing (120 – 1450 MHz)
- Four observing bands:
 - Band -2 (120 240 MHz)
 - Band -3 (250-500 MHz)
 - Band -4 (550-850 MHz)
 - Band -5 (1050-1450 MHz)
- 400 MHz instantaneous bandwidth
- Improved sensitivity (P=kTB watts, for noise-like signals)



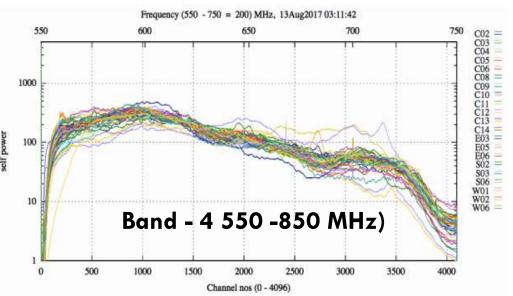


Image Courtesy: FE group + Control room

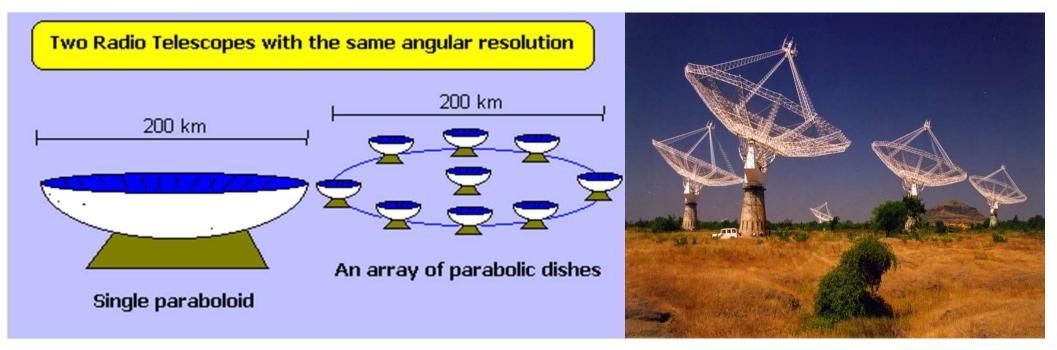
Angular Resolution: resolving distant objects

Resolve two distant objects in the sky

$$\Theta \sim \lambda/D$$

For a given wavelength, depends on the diameter of the telescope or maximum separation between two antennas

GMRT best resolution (L-band Synthesized beam): $\sim 2"$



Sampling the source signal through different apertures

Short Spacing Antennas of GMRT



Shortest spacing ~ 100 m; largest spacing ~ 25 km

GMRT Systems

GMRT Engineering Groups

Front-End

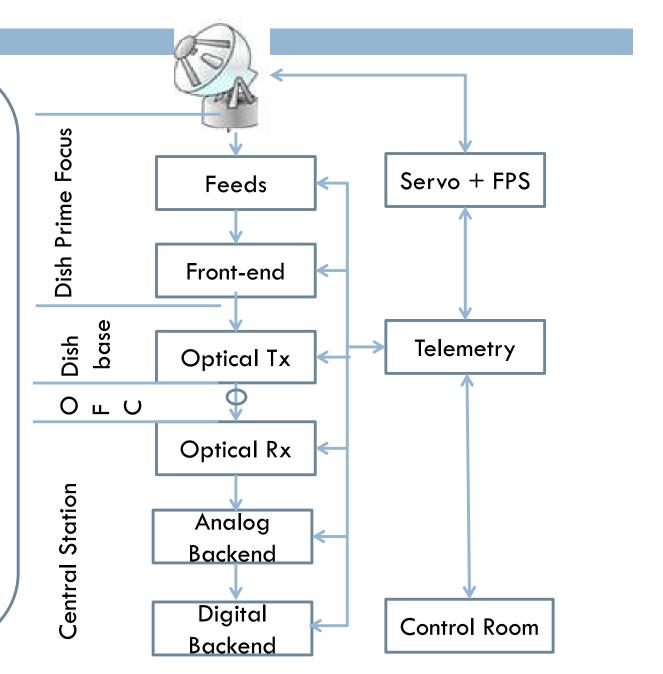
Backend

Servo

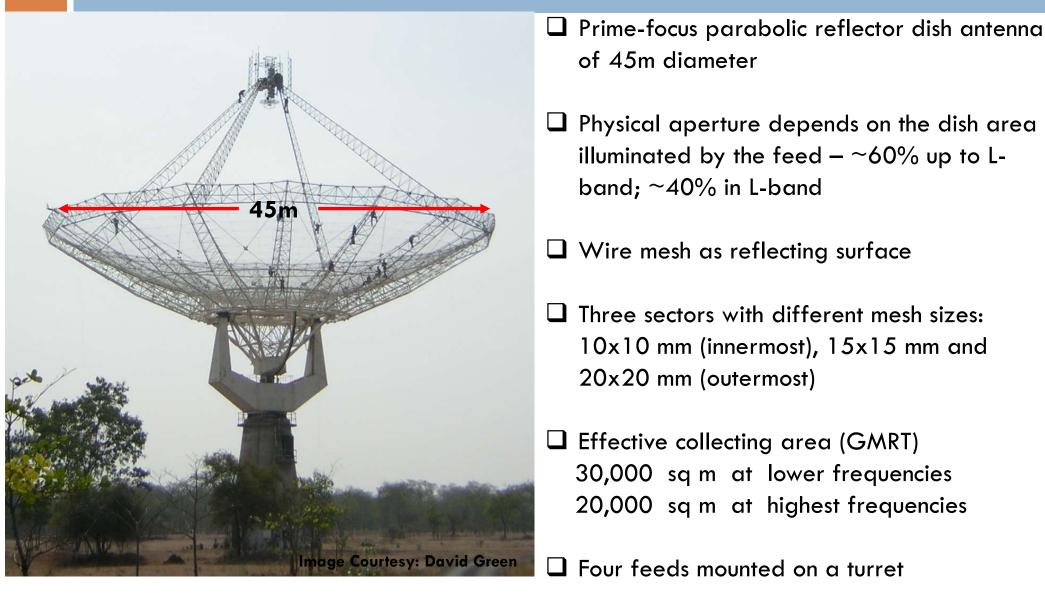
Mechanical

Electrical and Civil

Telemetry



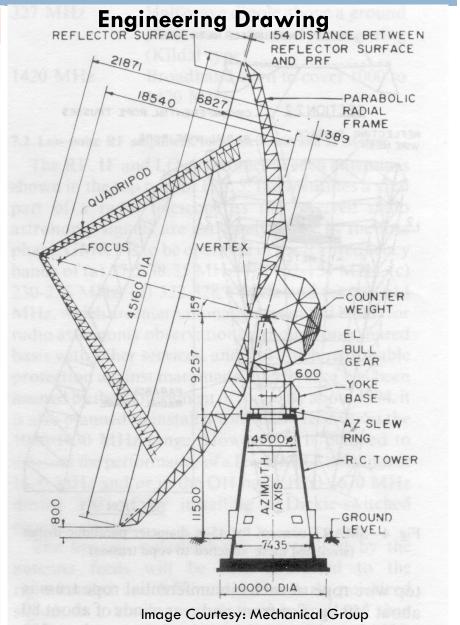
GMRT Antenna



One of the 30 dishes of GMRT

GMRT Antenna Parameters

| Parameter | Value |
|--------------------------------|---|
| Focal Length | 18.54 m |
| Physical Aperture | 1590 m^2 |
| f/D ratio | 0.412 |
| Mounting | Altitude – Azimuth |
| Elevation Limits | 17 to 110 degrees |
| Azimuth Range | ± 270 degrees |
| Slew Rates | Alt – 20 degree / min Az - 30 degree / min |
| Weight of moving structure | 82 tons + counter weight of 34 tons |
| Survival wind speed | 133 km/hour |
| RMS surface error | 10 mm (typical) |
| Tracking and Pointing Error | < 1'arc (up to 20 kmph) Few arc min(> 20 kmph) |

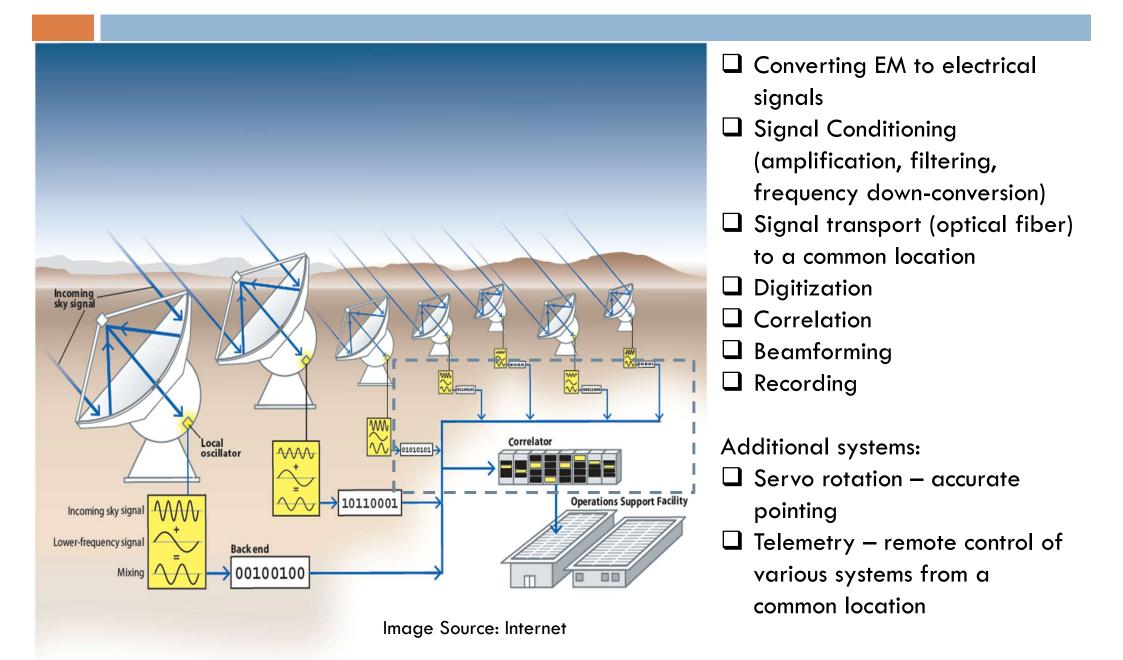


Dish and Reflecting Surface



- •7% solidity with 0.55 mm diameter Stainless Steel (SS) wires spot-welded at junction point to form a surface with 10x10 / 15x15 / 20x20 mm wire-grid.
- •Mesh panel supported by SS rope trusses attached to tubular parabolic frame: SMART (Stretched Mesh Attached to Rope Trusses) concept to form the parabola.

Radio Telescope: Overall Picture



Feeds and Front-end Electronics

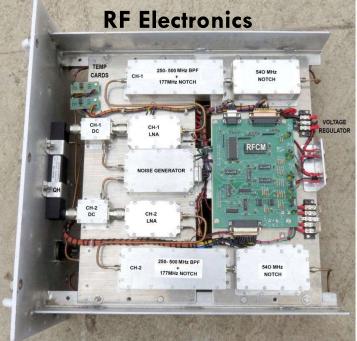


130 - 260 MHz (Dual Ring Feed)



250 – 500 MHz (Cone Dipole feed)

Feeds convert EM waves to electrical signal Electrical signal amplified using low-noise amplifiers (first stage)



Multi-stage amplification (~60 dB) at prime-focus

Image Courtesy: FE Group



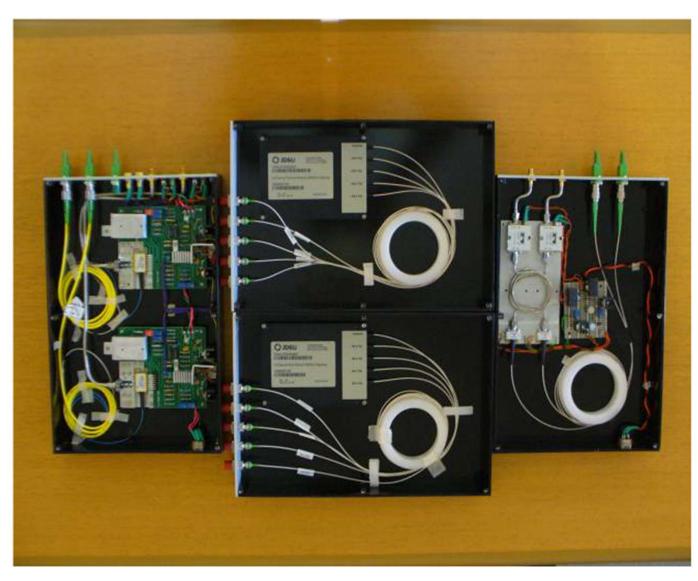
550- 900 MHz Cone Dipole feed



1000– 1450 MHz Horn Feed

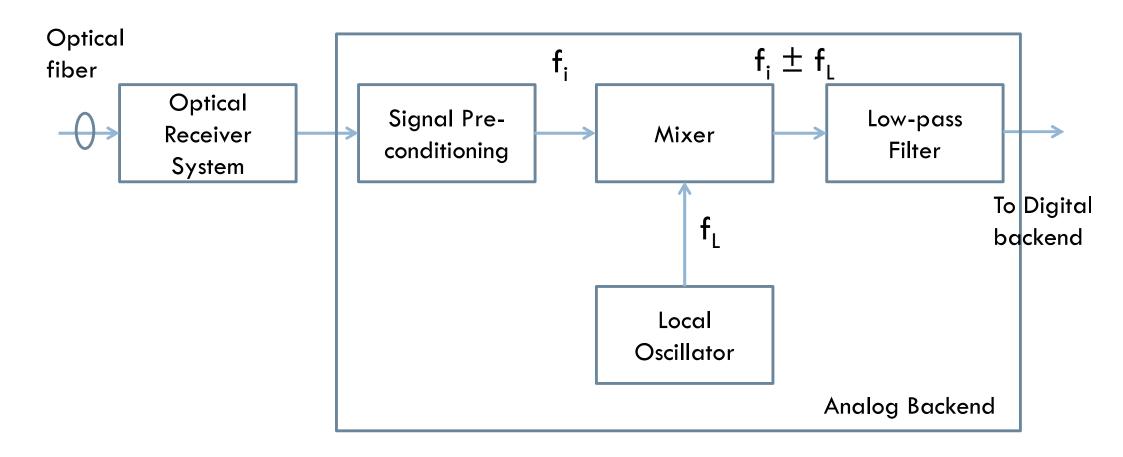
Fiber Optics System

- •First radio telescope to use analog fiber optic link for signal transport.
- •Fiber buried at a depth of 1.5m below the ground to reduce the effect of temperature on phase stability of the link.
- •Link distances vary from 200 m to 22 km.
- •Dense wavelength division multiplexing (DWDM) to accommodate multiple data and control channels on a single fiber.



Signal Processing in the Central Electronics Building

Signal Processing in Receiver Room

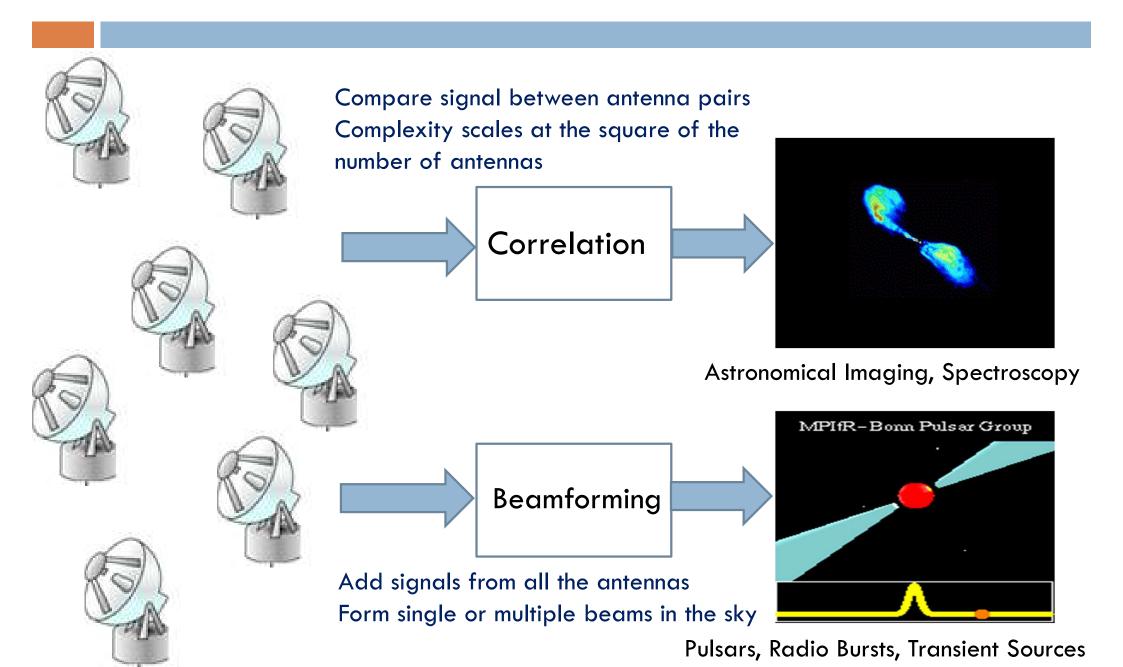


Analog backend amplifies the signal, converts from radio frequency to baseband through frequency heterodyning and provides desired bandwidth signal to the digital system

Baseband System - Installation



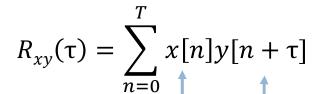
Correlation & Beamforming



Signal Correlation

Radio Source







Digitized signal from Antenna#1



Digitized signal from Antenna#2

Correlation gives information about the similarity between two signals - the common component contributed by the source Cross Correlate signals from antennas after correcting for the delay between them (τ) .

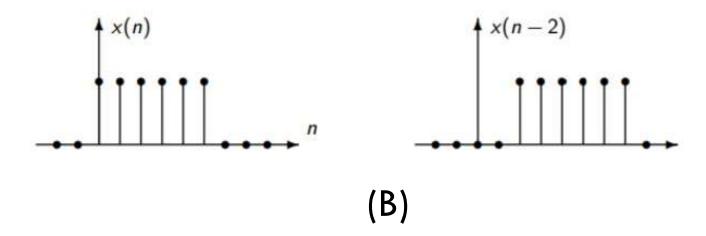
For N antennas, n(n-1)/2 cross-correlation operations are required. That makes it really complicated!

A computationally efficient method is to transform signals to frequency domain and multiply

Delay Correction

(A)

Time delay can be corrected by appropriately sliding the sequences in time domain Useful when the delay is integer multiple of the clock period

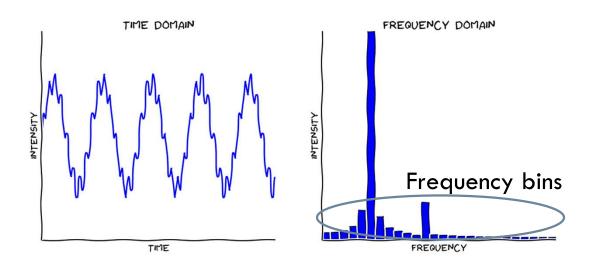


Can also be corrected by phase multiplication in the frequency domain Useful for correcting delays that are sub-multiple of the clock period

$$x(t-t_0) \stackrel{FT}{\longleftrightarrow} e^{-j\omega t_0} X(j\omega)$$

Correlation in the Fourier Domain

- ☐ Perform Discrete Fourier Transform (DFT) on the antenna signals
- \square Fast Fourier Transform computationally efficient algorithm for computing DFT (N² vs Nlog₂N)
- \square N-point transform provides a frequency resolution of (sampling freq. / N) Hz.



- Implementation resources and complexity increases with the number of points
- ☐ Frequency resolution depends on the type of observation. Usually the no. of points is of the range of 2048 to 32768 for wideband receivers

Signals in the Fourier domain are multiplied $X(\omega)Y(\omega)$ for getting the cross-correlation – this is done for each bin of antenna#1 with antenna#2 and so on.

Correlation of Complex Signals

- ☐ The output of FFT is complex number
- ☐ Complex multiplication is required for this each operation needs 4 multiplications and 2 additions

$$z_1 z_2 = (x_1 + iy_1)(x_2 + iy_2)$$

$$= x_1 x_2 + ix_1 y_2 + ix_2 y_1 + i^2 y_1 y_2$$

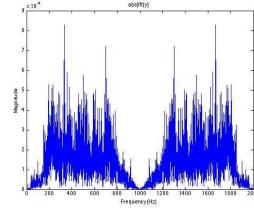
$$= (x_1 x_2 - y_1 y_2) + i(x_1 y_2 + x_2 y_1)$$

Image courtesy: http://www.thefouriertransform.com/math/complexmath.php

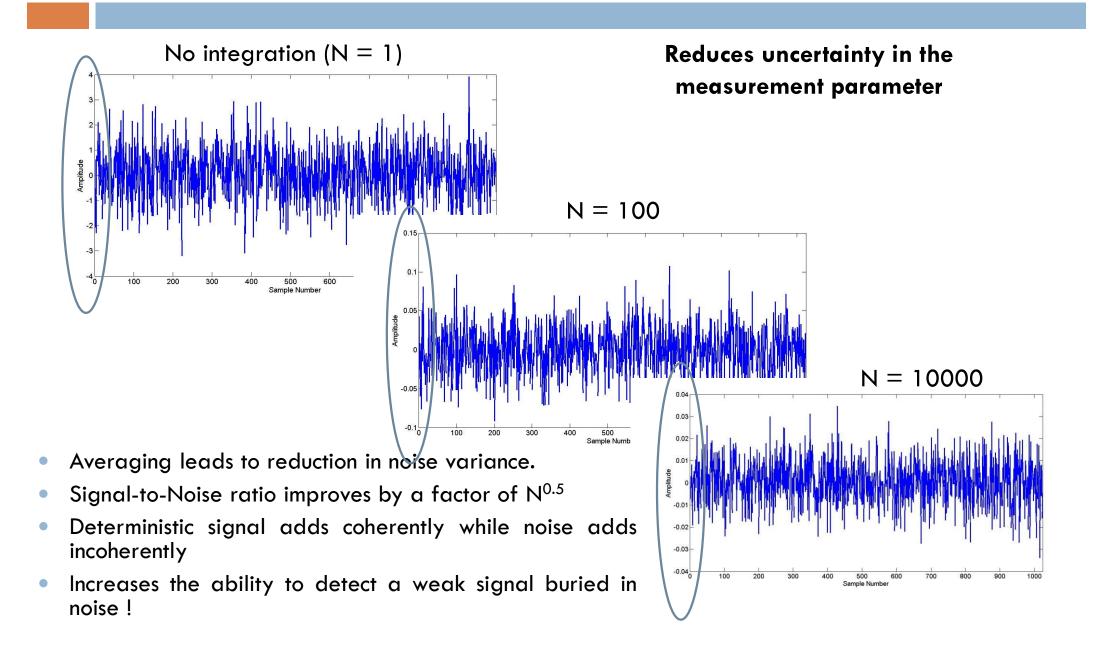
Since the input signal is real, the number of frequency bins contain redundant information are not used for further processing or correlation (conjugate symmetry property of DFT)

$$X(j\omega) = X^*(-j\omega)$$

□ Note: The above property does not hold if the input is a complex signal



Integration



Beamformer

 Power from individual antennas is added to form the incoherent beam (scalar addition)

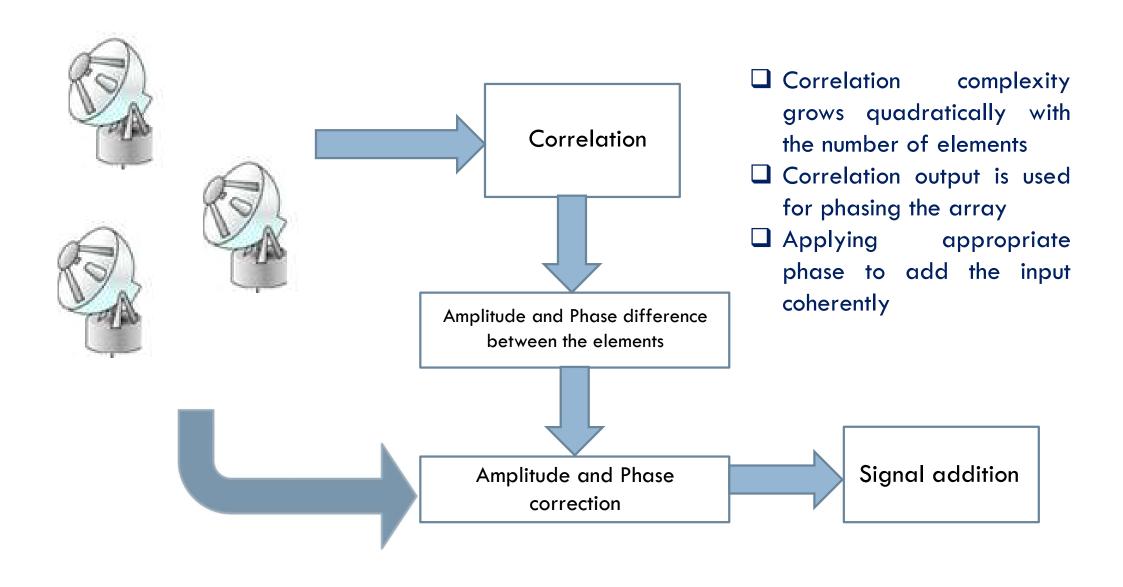
$$B_i = \sum_{i=0}^{n} (V_1^2 + V_2^2 + \dots + V_N^2)$$

 Voltages from individual antennas are added to form the coherent beam.

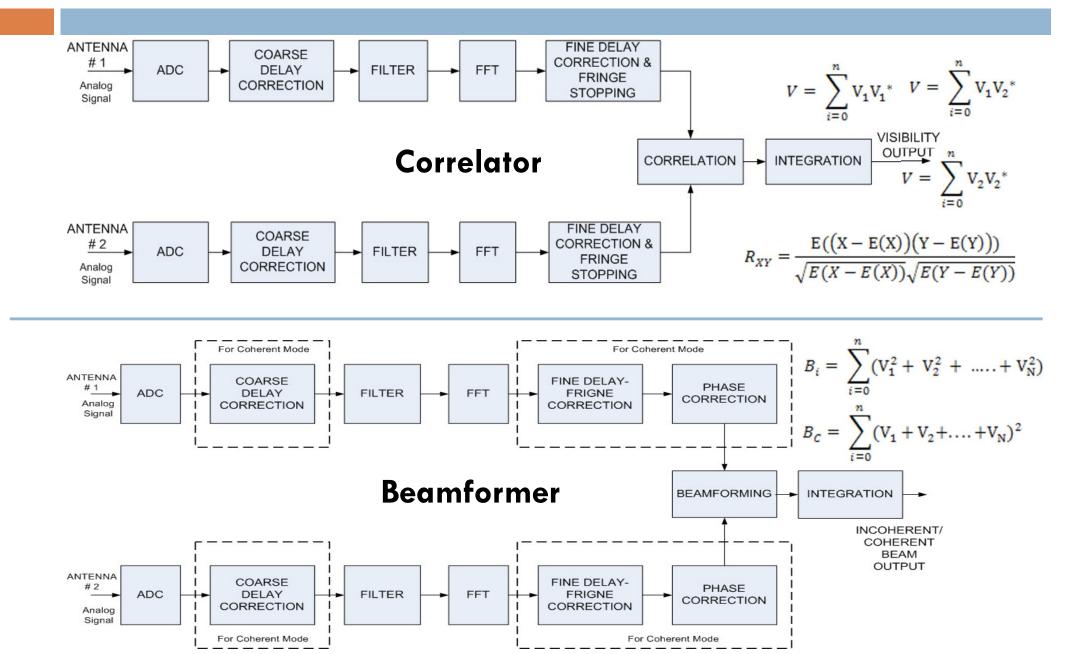
$$B_C = \sum_{i=0}^{n} (V_1 + V_2 + \dots + V_N)^2$$

Phase is important!

Beamforming in practice

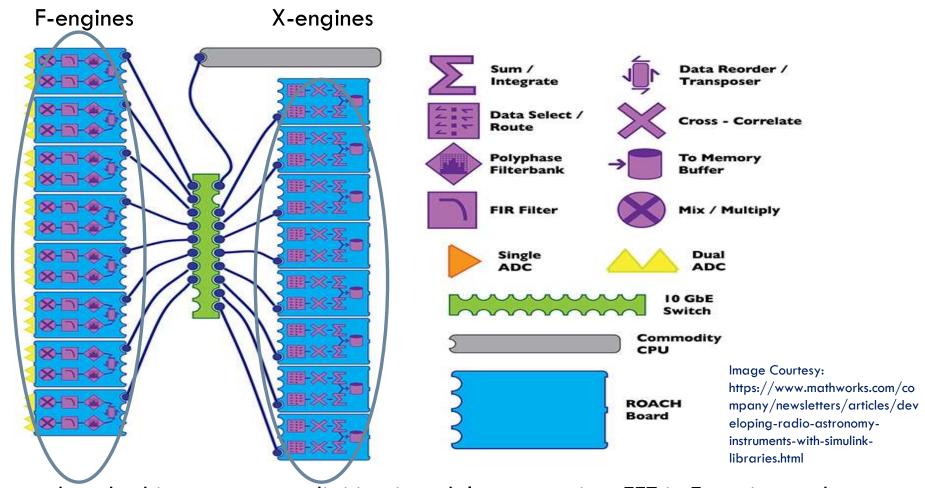


Digital Processing: Block Diagram



Modern Correlators: Example

Correlators consist of signal processing component and networking component



Commonly used method is to carry out digitization, delay correction, FFT in F-engine and multiplication and accumulation in X-engine. High speed data connectivity is required between the F & X engines

uGMRT Correlators: Installation





uGMRT correlator and beamformer: a combination of Field Programmable Gate Array (FPGA) and Graphics Processing Unit (GPU).

16-node cluster, computation of the order of \sim 10TFlops. Power consumption: \sim 20 kW



ROACH board

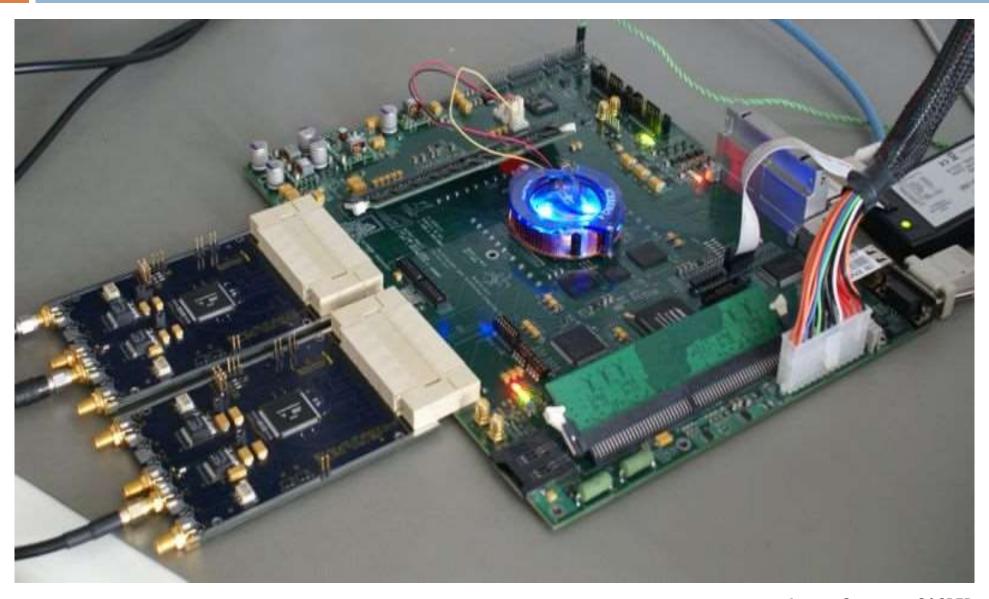


Image Courtesy: CASPER

FPGA and GPU

- Field-programmable gate array (FPGA) is an integrated circuit designed to be configured by a customer or a designer after manufacturing
- Configurable logic blocks and programmable interconnections for implementing digital circuits
- Generic design can be reconfigured to implement desired functionality
- Graphics Processing Unit (GPU) consists of many processor cores, much more than a CPU.
- Uses parallel processing to achieve high computational performance
- Performance usually measured in Floating Point Operations Per Second (FLOPS)

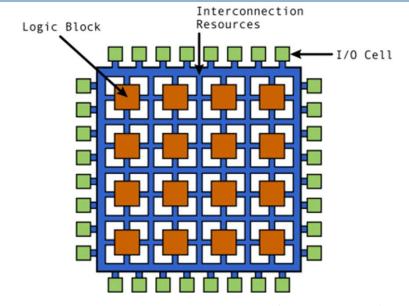
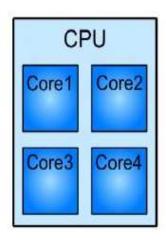


Image Courtesy: EE Times



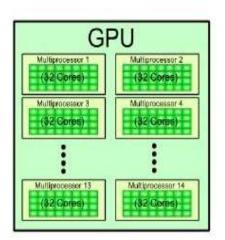
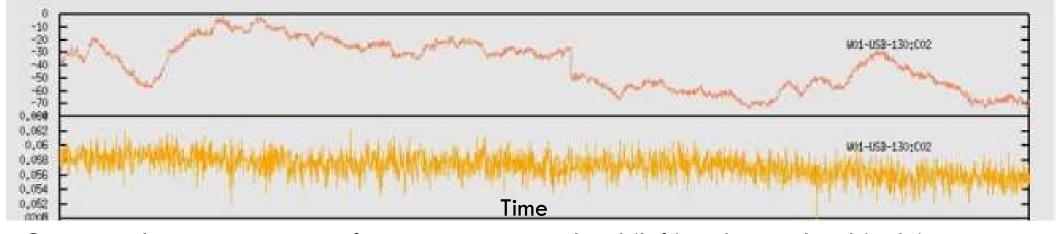
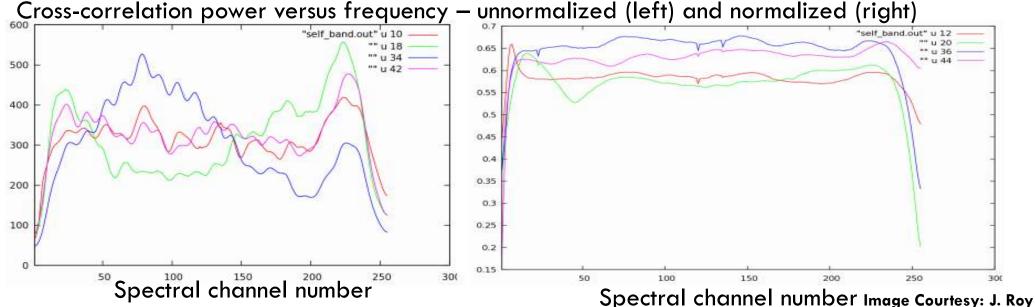


Image Courtesy: https://www.tutorialspoint.com/

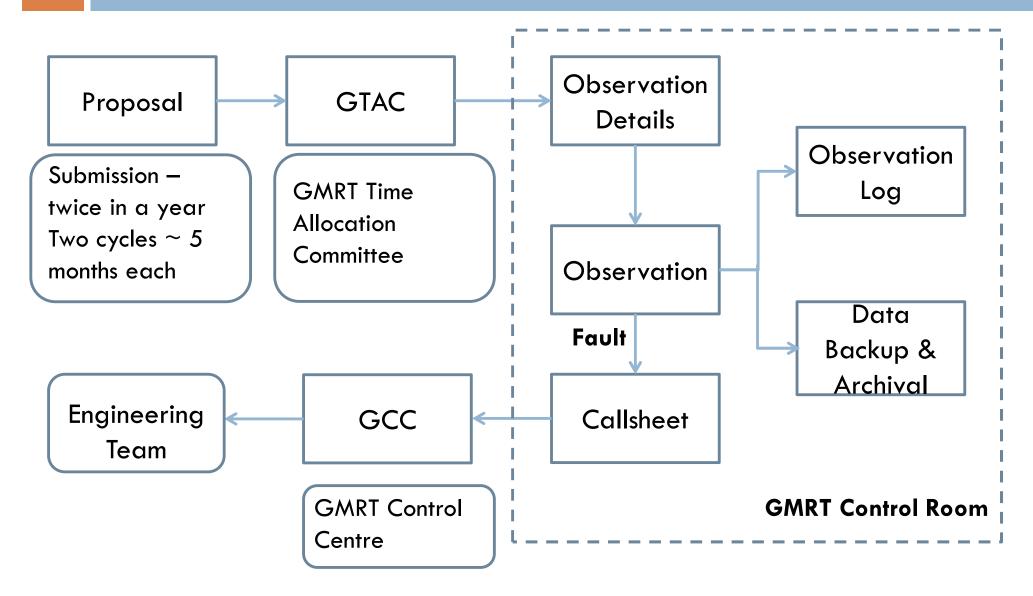
Correlator output (Example)

W01-C02 baseline cross-correlation amplitude (normalized) and phase for a single spectral channel (frequency) as a function of time





Control Room



NCRA Archival and Proposal System (NAPS) https://naps.ncra.tifr.res.in/naps/login

Servo System

- Points the antennas to any part of the sky and tracks a source
- •± 270° movement around azimuth axis and 17 to 110° above horizon about elevation axis
- •Slew speed of 30° / min in Az axis and 20° / min in El axis
- •RMS tracking and Pointing accuracy: 1 arcmin at 20 kmph wind speed
- Feed rotation and positioning system

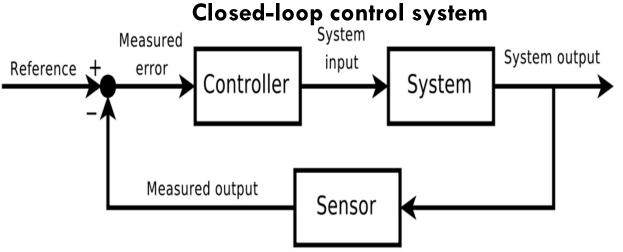






Image Courtesy: Servo Group

Maintaining and Upkeeping



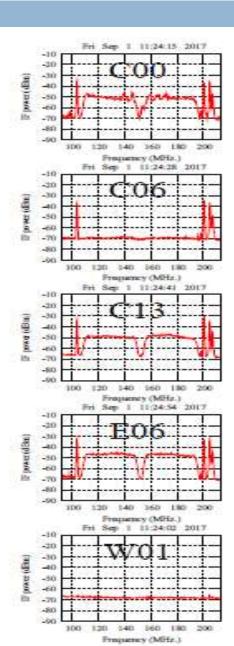
High Lift Platform for servicing front-end amplifiers, electronics and structural maintenance

Need a minimum number of antennas (26) for a fruitful scientific observation Day to day problem solving and longterm maintenance!

Painting: Very important for maintaining the health of the mechanical structure Takes ~3 months to paint one GMRT dish!



Diagnostic Tools



User Documents http://gmrt.ncra.tifr.res.in/~astrosupp/ Antenna Systems

GMRT Observer's Manual System Parameters and Current Status Polarisation observations with GMRT (V2) Dual band multi-pointing with GMRT (V2) GMRT Software Backend Documents uGMRT upgrade status

Before Observations

GTAC Schedule [NCRA] [GMRT]
White Slot Request[NCRA] [GMRT]
Command file Creater and Observations Setup
Line Observations Frequency Setup (tune)
Source(s) Rise and Set Time
Observing Time Calculator
VLA Calibrator Search
Dual band multi-pointing coordinates

During Observations

Online Archive (GOA)

Antenna Tracking Status
Corr band shapes and Project State *
Gain-amplitude and Phase (rantsol)
Visibility - amplitude and phase (xtract)
Antenna Wind Status
Satellite passes

After Observations

LTA to FITS conversion: AIPS help: RFI Plots: GDDP summary: Ondisplay Antenna Tracking Status
Ondisplay History
Feed position status
Pointing Offsets
Wind Monitoring Station
Antenna Wind Status
Temperature Status
Servo data
Electrical Power Status

Analog Backend GAB Status IF Band Shapes and Deflection data Grav Plots

Digital Backend

Corr band shapes and Project State Fringe Status (rantsol amp-gain) Gain-amplitude and Phase (rantsol) Visibility - amplitude and phase (xtract) Correlator Room Temperature

Gmon Tools, Logs

Test Results, Callsheets and Schedules

Useful scripts
Recent Callsheets
GMRT Upgrade Status
Results of Weekly PMQC tests
GDDP, RFI status gray plots
Antenna Beam Width Plots
Schedules and white slot request

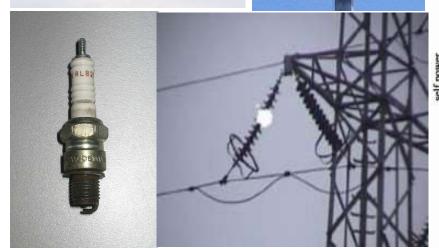
Challenge: Radio Frequency Interference



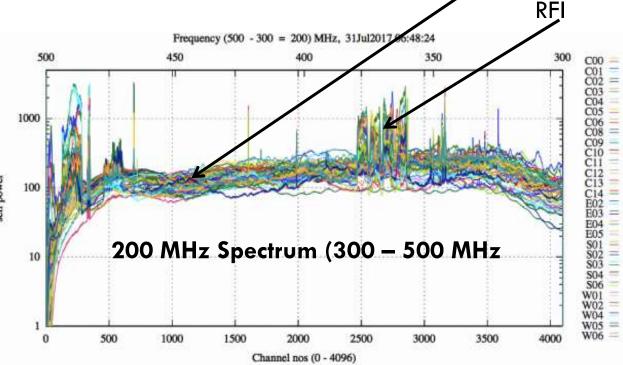
Image Courtesy: Wikipedia







- ☐ GMRT is a passive service receiver
- Due to large bandwidth and sensitive receiver systems, it is vulnerable to interference generated by various terrestrial and extra-terrestrial sources
- ☐ Radio Quiet zone around the array
- ☐ Located in a valley mountains provide RFI shielding from Pune and MumbaiSignal

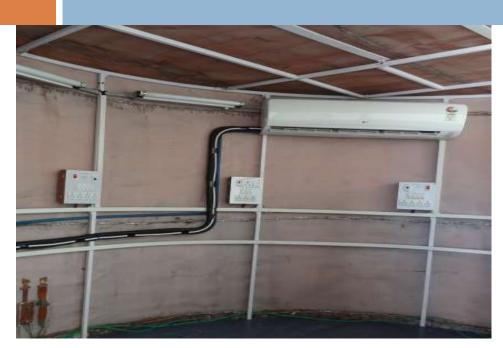


RFI at GMRT: Coexistence



Coexisting with surrounding villages, farmlands and other industries – the potential sources of RFI Image Courtesy: NCRA Archives

Mitigating Internal & External RFI

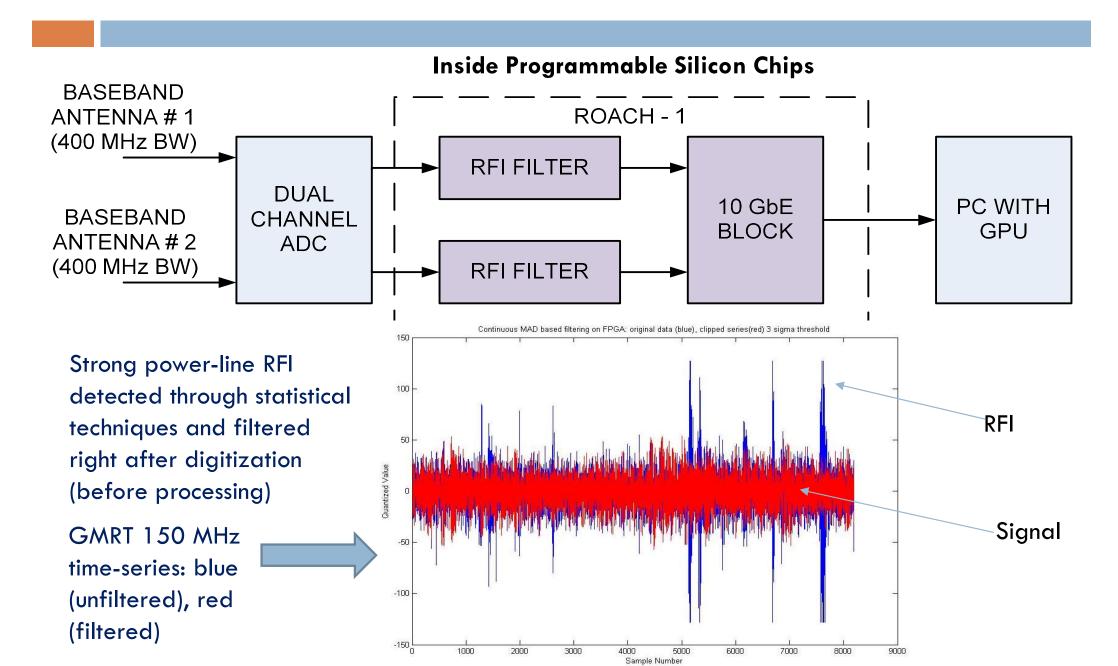






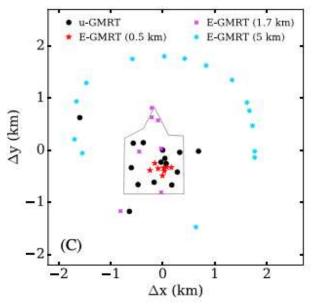


RFI Mitigation in digital system



Expansions to the existing uGMRT: eGMRT

Adding more antennas for baselines < 5 km



Improved sensitivity

Increase in Field-of-View depends on number of independent beams

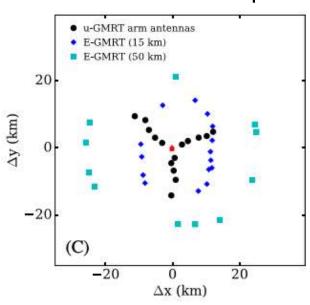
The Expanded GMRT (eGMRT)

Adding focal plane array on the GMRT antennas



Image Courtesy: K. Hariharan

Adding more antennas for baselines > 5 km and up to 50 km



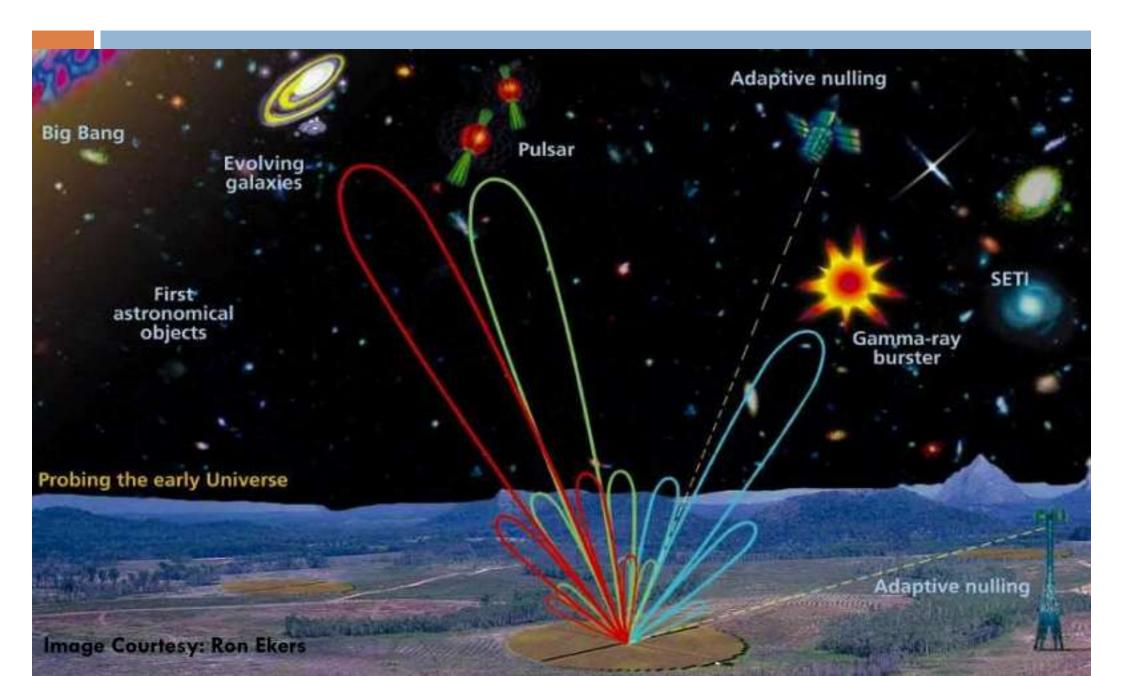
Improved angular resolution, lower confusion limit

Field-of-view is measured in degrees²

Increased Field-of-View

Source: Patra et al., EGMRT, MNRAS, 2019

Forming multiple beams: Advantages



References

- Lecture series on "Techniques of Radio Astronomy and GMRT", February-May 2016 https://www.gmrt.ncra.tifr.res.in/doc/Lectures/lectures.html
- 2. Low Frequency Radio Astronomy, 1997, ttps://www.gmrt.ncra.tifr.res.in/doc/WEBLF/LFRA/i ndex.html
- 3. http://gmrtscienceday.ncra.tifr.res.in/gsd2021/eng ineering_posters.php